

1. 2/15/86

ON LINE GRAPHS

THESIS

Submitted in Partial Fulfilment for the Degree
of
Master of Science in Mathematics



By

HEKMAT MOHAMED HESSEN ATABY

Mathematics Department
University College of Women
Ain Shams University

24/1/86

1986



وَقُلْ اَعْمَلُوا قَسِيْرَ مَا اَشَاءَ اللهُ مِنْكُمْ وَرَسُولُهُ وَالْمُؤْمِنُوْنَ
وَصَدَقَ اللهُ الْعَلِيْمُ



ON LINE GRAPHS

Supervisors

M. A. David

M. A. Seoud

A. Kar

Prof. Dr. A. Abdel Kar

Head of Mathematics Department

Soraya Sherif

~

COURSES

THE STUDENT HAS STUDIED THE FOLLOWING COURSES
AND PASSED THEM SUCCESSFULLY IN PARTIAL FULLFI-
LMENT FOR THE M.SC. DEGREE.

- | | |
|-------------------------|---------------|
| 1. Numerical Analysis | 3 h. per week |
| 2. Mathematical Physics | 3 h per week. |
| 3. Hydrodynamics | 3 h per week. |

Head of Mathematics

Department.

Soraya Sherif

Handwritten signature

ACKNOWLEDGEMENT

The author is indebted to Dr. Mohammed Abdel Azim Seoud, Ain Shams University, Faculty of Science, Mathematics Department, for suggesting the topic of this thesis and for his helpful guidance and stimulating advice throughout the supervision of this work.

The author is also grateful to Professor Dr. Abbas I. Abdel Karim, Professor of Mathematics, Ain Shams University for his kind help and continuous encouragement, throughout the supervision of this research work.

CONTENTS

	Page
SUMMARY	iii
 <u>CHAPTER I: ELEMENTS OF GRAPH THEORY</u>	
1.1. Definitions	2
1.2. Isomorphism of the graphs	5
1.3. Paths, circuits and valencies in graphs.....	5
1.4. Graphs and trees.....	8
1.5. Thickness	10
1.6. Eulerian and Hamiltonian graphs	12
1.7. Homeomorphic graphs, square and square roote of a graph	14
1.8. Crossing number ,girth and composition operation	16
 <u>CHAPTER II: SOME APPLICATIONS ON GRAPH THEORY</u>	
2.1. The minimal connector problem and the travelling salesman problem	19
2.2. The minimal articulated set	21
2.3. Some chemical applications	24
2.3.1. The correspondence between the graph and chemical terms	24
2.3.2. Molecular graphs and molecular topology...	25
2.4. Graph theory and molecular orbitals	26
2.5. Computation of characteristic polynomials of graphs	28

3

	Page
2.6. Caterpillar tree	30
2.7. Sexted polynomial	32
<u>CHAPTER III: BASIC RESULTS ON LINE GRAPHS</u>	
3.1. Introduction	35
3.2. Definition and characterization of line graphs.	37
3.3. Forbidden subgraphs in planar repeated line graphs	40
3.4. On line graphs and the Hamiltonian index	43
3.5. Hamiltonian line graphs	47
3.6. Graphs isomorphic to subgraphs of their line graphs	48
3.7. A 1-factorization of line graphs of complete graphs	51
3.8. The 1-factorization of some line graphs	52
3.9. Connected graphs switching equivalent to their iterated line graphs	52
3.10. Forbidden naked subgraphs	56
<u>CHAPTER IV: SOME REMARKS CONCERNING LINE GRAPHS AND ISOMETRIC GRAPHS</u>	
4.1. Abstract	58
4.2. Some notes on line graphs and isometric graphs.	58
4.3. Thickness of line graph	72
4.4. Two simple line graph equation	73
REFERENCES.	75

7

S U M M A R Y

SUMMARY

In entirely new theory, that of the diagrammatic "Graph" can be of great assistance in dealing with those combinatorial problems which occur in various economic, sociological, or technological fields. Indeed, the realization of the value of this "theory of Graphs" has given it a place of great importance in education. It is, perhaps, that aspect of the theory of sets which can produce the most fruitful results, not only for the "pure mathematician", but also for some other fields such as Engineering, organization, biology, psychology, sociology, geography, theoretical physics, nuclear physics, biomathematics, linguistics, zoology, computer science, anthropology and many others.

The recent years have witnessed a remarkable growth in the applications of graph theoretical principles to chemistry. There are several reasons for the increasing popularity of graph theory in chemistry. First, there is hardly any concept in the natural sciences which is closer to the notion of graph than the structural (constitutional) formula of a chemical compound, because a graph is simply said, a mathematical structure which

may be used directly to represent a molecule when the only property considered is the internal connectivity, i.e., whether or not a chemical bond joins two atoms in a molecule. Here, the chemical bond is represented by only a line connecting two atoms. Second, graph theory provides simple rules by which experimental chemists may obtain many useful qualitative predictions about the structure and reactivity of various compounds. Third, graph theory may be used as a foundation for the representation and categorization of a very large number of chemical systems. However, the language of graph theory is different from that of chemistry, we offer a short glossary in Table 2.4.1. Chapter 2, which contains the terminology of graph theory which we propose for standard use in chemistry and the corresponding chemical terms.

Here we discuss mainly "line Graphs" and something about "Isometric Graphs".

This thesis contains four chapters. The first chapter presents the main terms and concepts of graph theory, such as : graphs, complete graphs, bipartite graphs, circuit graph, isomorphism of the graphs, paths

circuits and valencies in graphs, subgraphs, trees, planarity, outerplanar and maximal outerplanar graphs, thickness, duality Eulerian and Hamiltonian graphs, subdivision graph homeomorphic graphs, crossing number, square of a graph, square root of a graph, clique graph, girth, the composition operation and regularity of graph.

In the second chapter some applications are presented such as the minimal connector problem and the traveling salesman problem. The minimal articulated set is discussed.

Some chemical applications, namely; the correspondence between the graph theoretical and chemical terms, molecular graphs, molecular topology, molecular orbitals, computation of characteristic polynomials of graphs, Caterpillar tree, the Clar graph, line graph and sextet polynomial are considered.

The third chapter deals with some basic results on line graphs, such as the characterization of line graphs, forbidden subgraphs in planar repeated line graphs, Hamiltonian index and the Hamiltonian line graphs. Graph isomorphic to subgraphs of their line

graphs, A 1-factorization of the line graphs of complete graphs and the 1-factorization of some line graphs, connected of graphs switching equivalent to their iterated line graphs, and the forbidden naked subgraphs are considered.

In the fourth chapter we studied some remarks and lemmas concerning line graphs and isometric graphs. An inequality for the thickness of a line graph is given. Also two simple line graph equations are discussed. This chapter is published in "The Journal of the Faculty of Education Ain Shams University, No.9, pp. 177-186, 1985".

11

CHAPTER 1

ELEMENTS OF GRAPH THEORY

CC

This chapter gives the basic definitions, theorems, and concepts of graph theory.

1.1. Definitions

(i) A simple graph G is defined to be a pair $(V(G), E(G))$ where $V(G)$ is a non-empty finite set of elements called vertices (nodes, or points), and $E(G)$ is a finite set of unordered pairs of distinct elements of $V(G)$ called edges (or lines); $V(G)$ is sometimes called the vertex-set and $E(G)$ the edge-set of G . For example, Fig. (1.1) represents the simple graph G whose vertex-set is the set

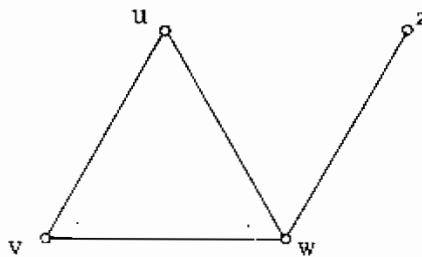


Fig. (1.1)

$\{u, v, w, z\}$ and whose edge set $E(G)$ consists of the pairs $\{u, v\}, \{v, w\}, \{u, w\}$ and $\{w, z\}$.

(ii) A graph whose edge-set is empty is called a null graph as shown in Fig. (1.2).



Fig. 1.2