



شبكة المعلومات الجامعية

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شبكة المعلومات الجامعية
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شبكة المعلومات الجامعية التوثيق الالكتروني والميكروفيلم



شبكة المعلومات الجامعية

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بالرسالة صفحات لم ترد بالاصل

AIN SHAMS UNIVERSITY
FACULTY OF ENGINEERING
Department of Electrical Power and Machines

High Efficiency Speed Control for DC Motor Using
Optimal and Adaptive Neural Network Controllers

B 5653

A thesis

Submitted in fulfilment for the Requirement
of the Degree of Doctor of Philosophy

By

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APPROVAL SHEET

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STATEMENT

This dissertation is submitted to Ain Shams University for the degree of Doctor of philosophy in Electrical Engineering.

The work included in this thesis is carried out by the author in the department of Power Electronics and Energy Conversion, Electronics Research Institute.

No part of this thesis has been submitted for a degree or a qualification at any other University or Institution.

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ABSTRACT

A separately-excited dc motor drive system has been used in the industrial field when a wide range and high accurate speed control is necessary. The majority of the installed electric machines operate at two thirds or less of their nominal load. Consequently, need for efficiency improvement is significant. The profit from energy savings is considerable. The energy saving in electric motors is achieved by either designing an energy-efficient motor, or driving the conventional motor under high-efficiency conditions. The ratio of the armature current and the field current that gives the maximum efficiency is analytically derived. Two control techniques adopted in this thesis for high efficiency speed control of the dc motor. First, the improved optimal regulator theory is applied to the system. The MATLAB SIMULINK software package is utilized for simulating the system performance. Efficiency improvement is achieved specially at light load conditions with adequate transient response.

As the research in artificial neural networks has been recently active and gives more opportunities for control applications, a second method which uses a neurocontroller to obtain the high efficiency operation is adopted. Armature speed control using adaptive neural network is presented, both by simulation and experimental implementation, as a step to generalize the study for high efficiency operation. Robust and adequate steady state and transient performance are achieved.

The high efficiency neural network controller is simulated and experimentally implemented using microcomputer with data acquisition card (PC 30 AT).

A neural network software program is developed to adjust the ratio of the field and armature currents for the purpose of obtaining high efficiency.

Comparison between theoretical and experimental results are carried out and good agreement is observed.

The obtained simulation and experimental results show adequate and robust dynamic performance of the system.