Ain Shams University
Faculty of Computer
& Information Sciences
Computer Science Department



Enhancement of Motion Deblurring Algorithms in single images

A thesis submitted to the Department of Computer Science, Faculty of Computer and Information Sciences, Ain Shams University, in partial fulfillment of the requirements for the degree of Master of Computer and Information Sciences

By:

Salsabil Amin El-Regaily

B.Sc. in Computer Science, Faculty of Computer and Information Sciences, Ain Shams University. Cairo, Egypt

Supervised By:

Prof. Dr. Mohamed Ismail Roushdy

Computer Science Department, Faculty of Computer and Information Sciences, Ain Shams University

Dr. Mohamed Hassan Abd El-Aziz

Basic Sciences Department, Faculty of Computer and Information Sciences, Ain Shams University

Dr. Haitham ELMessiry

Computer Science Department, Faculty of Computer and Information Sciences, Ain Shams University





تحسين خوارزميات إزالة الطمس الناتج عن الحركة في الصور المنفرده

رسالة مقدمة الى قسم علوم الحاسب بكلية الحاسبات والمعلومات جامعة عين شمس كجزء من متطلبات الحصول على درجة الماجستير في الحاسبات والمعلومات

إعداد

سلسبيل أمين يس الرجيلي

معيدة بقسم العلوم الأساسية بكالوريوس علوم الحاسب كلية الحاسبات و المعلومات جامعة عين شمس القاهرة

تحت إشراف

د. محمد حسن عبدالعزيز
 أستاذ مساعد بقسم العلوم الأساسية كلية الحاسبات والمعلومات
 جامعة عين شمس.

أ.د. محمد اسماعيل رشدي
 عميد كلية الحاسبات والمعلومات والأستاذ بقسم علوم الحاسب
 جامعة عين شمس.

د. هيثم محمد المسيري
 أستاذ مساعد بقسم علوم الحاسب كلية الحاسبات والمعلومات
 جامعة عين شمس

Publications

The work presented in this thesis has been published in the following conferences:

- S. El-Regaily, H. El-Messiry, M. Abd El-Aziz and M. Roushdy, "Linear Motion Deblurring from Single Images using Genetic Algorithms",14th International Conference on Aerospace Sciences & Aviation Technology (Asat – 14), Military Technical College, Cairo, Egypt, ID: 204-Ip, 24th May 2011.
- S. El-Regaily, H. El-Messiry, M. Abd El-Aziz and M. Roushdy, "Non-Linear Motion
 Deblurring from Single Images using Genetic Algorithms ",8th International Conference
 on Electrical Engineering (ICEEng-8), Military Technical College, Cairo, Egypt, ID:
 EE120, 29th May 2012.
- S. El-Regaily, H. El-Messiry, M. Abd El-Aziz and M. Roushdy, "Single Image Motion Deblurring using Genetic Algorithms", 29th National Radio Science Conference (NRSC), Faculty of Engineering, Cairo University, Cairo, Egypt, pages 325 – 333, 10th April 2012.
- S. El-Regaily, H. El-Messiry, M. Abd El-Aziz and M. Roushdy, "Using GPU-Accelerated Genetic Algorithm for Non-Linear Motion Deblurring in a Single Image", 8th International Conference on Informatics and Systems (INFOS), Faculty of Computer and Information Sciences, Cairo University, Cairo, Egypt, pages BIO-174 BIO-180, 14th May 2012.

Abstract

One of the key problems of restoring a degraded image from motion blur is the estimation of the unknown blur filter. Several algorithms have been proposed utilizing image intensity or gradient information. The unknown blur filter could be linear, shift in-variant filter that could be characterized with only two parameters; the motion direction and the blur length. Or it could be non-linear, shift-variant filter that has no specific behavior. There has been much work dealing with motion blur with both of its types.

This thesis proposes an algorithm for restoring the motion blurred image using Genetic Algorithms. It works on both, the linear and the non-linear motion blur, separately. In the linear part, the direction and the length of the motion blur are used as the parameters of the Genetic Algorithm. The method assumes a uniform linear camera blur over the image. In the non-linear part, the blur kernel has no specific behavior, so each pixel value in the kernel is considered as a parameter to the algorithm.

A Graphics Processing Unit Accelerated version of the Genetic Algorithm is presented at the end of the thesis that achieved a huge speedup in the running time. The accelerated algorithm works 12.6x faster than the standard Genetic Algorithm.

Experiments on a wide data set of standard images degraded with different length kernels demonstrate the efficiency of the proposed approach especially in small blur lengths compared to other algorithms.

Table of Contents

Publications	II
Abstract	III
List of Figures	VI
List of Tables	X
List of Abbreviations	XI
Chapter 1 Introduction	1
1.1 PROBLEM DEFINITION	1
1.2 TARGET OF THE THESIS	
1.3 THESIS ORGANIZATION	
Chapter 2 Motion Blur	
2.1 INTRODUCTION	4
2.2 FUNDAMENTAL RESOLUTION TRADEOFF	5
2.3 MOTION BLUR MODEL	6
2.3.1 Point Spread Function Definition	7
2.4 TYPES OF MOTION BLUR	7
2.4.1 Linear Motion Blur	
2.4.2 Survey of Linear Motion Deblurring Algorithms	
2.4.3 Non-Linear Motion Blur	
2.4.4 Survey of Non-Linear Motion Deblurring Algorithms	
2.5 SUMMERY	
Chapter 3 Image Deconvolution	16
3.1 INTRODUCTION	16
3.2 FAMOUS DECONVOLUTION TECHNIQUES	
3.2.1 Wiener deconvolution	
3.2.2 Regularized Filter	
3.2.3 Gaussian Prior	
3.2.4 Sparse Prior	23
3.3 THE LUCY-RICHARDSON DECONVOLUTION ALGORITHM	23
3.4 SUMMERY	25
Chapter 4 Genetic Algorithm	26
4.1 INTRODUCTION	
4.2 STAGES OF THE GA	27
4.2.1 Creating the first generation	
4.2.2 Reproduction	
4.2.3 Crossover	
4.2.4 Mutation	
4.2.5 Elitist selection	
4.3 STRUCTURE OF THE ALGORITHM	
4.4 RELATED WORK IN GA	
4.5 SUMMERY Chapter 5 Applying Genetic Algorithm to Linear Motion Deblurring	
5 1 INTRODUCTION	33

5.2 THE GOAL FUNCTION	34
5.2.1 Using the original image	35
5.2.2 Using the best previous image	
5.2.3 Using the average of the best previous images	
5.2.4 Including a Regularization term	
5.2.5 Other terms added to the goal function	
5.2.6 Cross Correlation	
5.2.7 Changing Deconvolution techniques	
5.2.8 Norm of errors between blurred images	
5.3 RINGING ARTIFACTS	
5.4 IMPLEMENTATION AND EXPERIMENTAL RESULTS	
5.4.1 "Linear Motion Blur Parameter Estimation in Noisy Images using Fuzzy Sets and Power	
Spectrum" Technique by M. Moghaddam et al	48
5.5 SUMMERY	
Chapter 6 Applying Genetic Algorithm to Non-Linear Motion Deblurring	
Chapter o Applying Genetic Algorithm to Non-Emedi Motion Depluring	
6.1 INTRODUCTION	5 0
6.2 DIFFERENT TRIALS OF THE GOAL FUNCTION	
6.2.1 8-Neighbourhood rule	
6.2.2 The Multi-scale Approach	
6.2.3 Maximizing Contrast	
6.2.4 Shock Filters	
6.2.5 Gradients Histogram 6.3 EXPERIMENTAL RESULTS AND COMPARISONS	
6.3.1 "Remove Camera Shake from a Single Photograph" technique	
6.3.2 Results and Comparisons	
6.3.3 Colored Images	
6.4 SUMMERY	
Chapter 7 GPU-Accelerated Genetic Algorithm	80
7.1 INTRODUCTION	
7.2 GPU -ACCELERATED GA SPEEDUP	
Chapter 8 Conclusion and Future Work	84
8.1 CONCLUSION	
8.2 FUTURE WORK	85
References	86

List of Figures

Figure 2.1 Different camera motions lead to different motion blurs. (a) The original image. In	(b)
and (c), the scene is blurred by linear horizontal and vertical motions, respectively. (d)The sc	ene
is blurred due to circular motion	5
Figure 2.2 Fundamental tradeoff between spatial resolution and temporal resolution of an	
imaging system	6
Figure 2.3 (a) is a part of an unblurred image, and the corresponding step signal, figure 2.3 (b)	o) is
the image in (a) blurred in the horizontal direction, and the corresponding ramp signal	7
Figure 2.4 illustration of a PSF as a function of x, y and energy	7
Figure 2.5 Examples for linear motion blur. (a) Original Barb image, (b) The Barb image blurre	ed
with direction 45° and length 13 pixels, (c) the Barb image blurred with direction 0° and length 13° and	ţth
15 pixels	9
Figure 2.6 (a) An image blurred with direction 0º and length 10 pixels. (b) Fourier Spectrum of	of
the blurred image in (a)	9
Figure 2.7 (a) Cepstrum of an image blurred with 75°. (b) Line drawn from the origin to the	
negative peak	10
Figure 2.8 Represents the different k-tap models	11
Figure 2.9 Two different non-linear kernels of size 21	
Figure 3.1 The process of deconvolution	16
$\textbf{Figure 3.2} \ \textbf{In blind deconvolution, both the original image and the blurring PSF are unknown}$	17
Figure 3.3 Regularized filter results. (a) Original image, (b) Blurred image, (c) Restored image	ž
using the true PSF	
Figure 3.4 Comparison of deblurring algorithms applied to the image in (a)	23
Figure 3.5 Lucy-Richardson Deconvolution. (a) Original image, (b) Blurred image, (c) Restored	k
image with the lucy-richardson algorithm	
Figure 4.1 The idea of selection to the new generation using a random number generator. If	we
have a spinning arrow (representing the random number generated), then it's most probable	е
that it will point at john's part most of the times, because he has the biggest portion in the	
chart	
Figure 4.2 Symbolic example of crossover	
Figure 4.3 Flowchart of the proposed GA	
Figure 4.4 Expectation of the GA work (a) The original PSF kernel, (b) Initialization of the blur	_
PSF, (c) PSF after some generations (d) The resulting PSF of the GA	
Figure 5.1 A look into processes inside a generation	34
Figure 5.2 (a) Original Baboon image (b) The Baboon image blurred with direction 140º and	
length 15 pixels. (c) The result of GA with goal function that uses the original image, with	
direction 1300 and length 15 nivels	36

Figure 5.3 (a) Original Cameraman image, (b) The Cameraman image blurred with direction 33º
and length 17 pixels. (c) The result of GA with goal function that uses the previous image with
the min error, with direction 35º and length 15 pixels
Figure 5.4 (a) The baboon image blurred with direction 140 and length 15. (b) The result of
Moghaddam [6] with estimated direction 136° and length 13 pixels. (c) The final result of GA
that computes the average of the best images that the algorithm converged to
Figure 5.5: (a) Original Bird image (b) The Bird image blurred with direction 55º and length 11
pixels. (c) The result of adding a regularization term to the goal function with direction 66° and
length 9 pixels39
Figure 5.6 (a) Original Barb image, (b) The Barb image blurred with direction 45º and length 13
pixels. (c) The result of adding a regularization term to the goal function with direction 84º and
length 5 pixels39
Figure 5.7:(a) Original Girl image, (b) The Girl image blurred with direction 170° and length 9
pixels. (c) The result of maximizing the entropy as the goal function with direction 105º and
length 5 pixels
Figure 5.8 The results of the cross-correlation of the original image, blurred image, and the
restored image respectively with themselves. Note that the original image has the sharpest
peak41
Figure 5.9 (a) and(b) are the results of the cross correlation of one vertical line (column) and one
horizontal line (row) each with itself, of the original Baboon image. (c) and (d) are the results of
the cross correlation of one vertical line (column) and one horizontal line (row) each with itself
of the blurred baboon image. The blur length and direction are 17 pixels, 135°. Note the smooth
peak in both the row cross correlation and the column cross correlation. (e) and (f) are the
results of the cross correlation of one vertical line (column) and one horizontal line (row) each
with itself of the restored baboon image, with parameters: 15 pixels, 130°. The peeks are
Sharper than the blurred correlation and still smoother than the original correlation
Figure 5.10 (a) Original Baboon image (b) The Baboon image blurred with direction 140º and
large length 15 pixels. (c) The GA result with direction 137º and length 5 pixels
Figure 5.11 (a) Original Barb image. (b) The blurred Barb image with direction 45° and small
length 5 pixels. (c) The final result of GA with direction 44º and length 5 pixels
Figure 5.12 (a) Original Bird image. (b) The bird image blurred with direction 165° and length 15
pixels. (c) The bird image restored with the correct parameters, direction 165° and length 15
pixels. Notice the strong ringing effect. (d) The bird image chosen in the algorithm with direction
164° and length 7 pixels. Notice light ringing effect that leads to a less error value
Figure 5.13 The post-processing ringing removal algorithm in [77]
Figure 5.14 Goal function values (errors) of the best entities over generations describe the
convergence of the GA48
Figure 5.15 An example of a SINC function. SINC function is usually modeled as $\sin(x)/x$ at any
position except at 0 where $SINC(0) = 1$
Figure 5.16 (a), (b) The original image and its Fourier spectrum. (c) The blurred image with
motion orientation 45° and motion length 10 pixels. (d) Fourier spectrum of image(c). (e) Image
5 ,

lurred with motion length of 10 $^{ m e}$ pixels and 0 $^{ m e}$ orientation. (f) The Fourier spectrum of image	5
.)	. 51
gure 5.17 Radon transform of an image blurred with direction 45°45°	. 51
gure 5.18 The SINC structure in f(x)	. 52
gure 5.19 The noisy image and it's Fourier transform. Notice the white line that determines	
ur direction in the Fourier transform	. 52
gure 5.20 our implementation of [6]: (a) The original Boat image. (b) The Boat image blurred ith direction 45° and length 13 pixels, (c) The Fourier spectrum of (b), notice the angle etween dark lines and horizontal axis. (d) The radon transform of (b), notice the highest value of the radon transform 'in dark red' at 46°. (e) The 'f(x)' function calculated from Fourier opertrum and z-function, notice the two valleys around central peak. (f) The final result with estimated direction 46° and length 14 pixels. The RMSE is 7.109	. 54 . 55 n 7 on
gure 5.23 (a) The original San image (b) The blurred image with direction 55° and large blur ngth of 15 pixels, (c) The result of [6] with direction 46° and length 14 pixels, and (d) GA resith direction 65° and length 5 pixels	ult . 56 ı [6]
gure 6.1 (a) The blurred Cameraman image, (b) The restored Cameraman image using the 8 eighbourhood rule, with the corresponding blur PSF and estimated PSF	. 60 ale The as
gure 6.3 (a) A low contrast image with its corresponding histogram (b) The same image in (a ut in high contrast and a stretched histogram	a) . 63 ne . 05. . 64 . 65
gure 6.7 Heavy-tailed distribution of an original and blurred image from [17][17]	. ხ/

Figure 6.8: (a) The original image, (b) The blurred image, (c) The restored image using the new	
gradient histogram term, (d) A comparison between gradient histograms of the original, blurred	t
and restored images 6	7
Figure 6.9 Mixture of Gaussians fit to empirical distribution of image gradients	9
Figure 6.10 Image Reconstruction algorithm in [17]	0
Figure 6.11 (a) Blurred baboon image and the blur kernel, (b) GA result with RMSE 8.811, (c)	
Result of [17] with RMSE 8.39 7	2
Figure 6.12 (a) Blurred lena image and the blur kernel, (b) GA result with RMSE 6.58, (c) result	
of [17]with RMSE 6.46 7	2
Figure 6.13 Goal function minimum values (errors) of the best entities over generations describ	e
the convergence of the GA7	2
Figure 6.14 Change of RMSE of restored images with increase in kernel size for both GA and	
Fergus et al. [17]	3
Figure 6.15 Change of running times with increase in kernel size for both GA and Fergus et al.	
[17] 7	3
Figure 6.16 Change of estimated kernels RMSE with increase in kernel size using GA and Fergus	
et al. [17]7	4
Figure 6.17 Change of images RMSE with increase in image resolution using GA and Fergus et al	١.
[17] 7	4
Figure 6.18 change of running times with increase in image resolution for both GA and Fergus e	:t
al. [17]	'5
Figure 6.19 change of estimated kernels RMSE with increase in image resolution using GA and	
Fergus et al. [17]	'5
Figure 6.20 Results for a small 256 Boat image blurred with kernel size 9 (a) the blurred image,	
(b) the result of [18], (c) result of [30] and (d) result of GA	7
Figure 6.21 Results of a large size Taj image blurred with kernel of size 21 (a) the blurred image,	
(b) result of [18], (c) result of [30] and (d) result of GA	8
Figure 6.22 (a) the original 512×512 Lena image (b) the blurred image and the blurring PSF (c)	
the restored image using GA and the estimated PSF7	8
Figure 7.1 Flowchart of the GPU-Accelerated GA8	2
Figure 7.2 Comparison of running times between standard GA, Fergus et al.[17] and GPU-	
Accelerated GA	2

List of Tables

Table 5.1 shows the blur lengths and the algorithm behavior toward each length in terms of t	:he
estimated length, the average error of estimated direction, and the average RMSE between t	he
original image and the estimated images	. 48
Table 5.2 The estimated direction and blur length with the Root Mean Square Errors for the	
proposed GA compared with the algorithm in [6]	. 53
Table 6.1 Number of runs of GA and Fergus et al. [17]	. 71
Table 6.2 The percentage of better RMSE and running time of GA over the algorithm in [17]	
after being applied to all images in the generated database	. 71
Table 6.3 type I and type II errors for the GA with the algorithm in [17]	. 76
Table 6.4 some comparisons for the GA with algorithms in [18] and [30]	. 76
Table 7.1 speed up of individual functions achieved using GPU-Accelerated GA	. 82

List of Abbreviations

GA: Genetic Algorithm

PSF: Point Spread Function

LCD: Liquid Crystal Display

MAP: Maximum A Posteriori

MDF: Motion Density Function

ISD: Iterative Support Detection

SNR: Signal to Noise Ratio

IID: Independent and Identical Distributed

RMSE: Root Mean Squared Error

IOAC: Index Of Area Coverage

GPU: Graphics Processing Unit

Chapter 1 Introduction

1.1 Problem Definition

One of the most common artifacts in digital photography is motion blur caused by the relative motion between the camera and the scene during image exposure time. The problem is particularly apparent in low light conditions when the exposure time can often be in the region of several seconds, and the inevitable result is that many of our snapshots come out blurry and disappointing [1]. Many photographs capture ephemeral moments that cannot be recaptured under controlled conditions or repeated with different camera settings. If camera shake occurs in the image for any reason, then that moment is lost. One solution that reduces the degree of blur is to capture images using shorter exposure intervals. This, however, increases the amount of noise in the image as the required amount of light is not collected.

Motion Deblurring is a problem that has been extensively studied recently, to restore a close estimate to the original image from its blurred version only. That is called blind deconvolution, which is a very difficult problem because there will be larger number of unknowns.

Applications of Motion Deblurring:

- *Common Photography*: to restore Images and videos corrupted by the motion blur while capturing them by normal cameras.
- **Surveillance:** to clarify images of moving objects or humans [2].
- *Radars*: to restore the blurry numbers of license plates of fast moving vehicles on the roads and highways [3].
- *Text Recognition*: can be used as a part of the text recognition problem to enhance and sharpen the output text [4].

1.2 Target of the Thesis

In this thesis, restoration of a motion blurred image is investigated. It is required to find the blurring kernel that caused the degradation from a single input blurred image without previous knowledge about the original image. Genetic Algorithm (GA) is used to optimize the solution and reach the best blurring kernel. The work is divided into two main categories: linear motion blur estimation, and non-linear motion blur estimation, as the linear blur kernel has much less parameters than the non-linear kernel, which leads to less computational time and less needed resources.

GA has been used recently in image restoration in general, but not in particular for motion blur removal. The algorithm has to be well suited for each problem that is being investigated, while still having its general structure. Some modifications to normal GA had to be added in order to suite the nature of our problem.

As slow running time is a main disadvantage to GA, a Graphics Processing Unit-Accelerated version of the Genetic Algorithm is presented. The accelerated version achieved a huge speedup in the running time as it works 12.6x faster than the standard GA. Experiments on a wide data set of standard images degraded with different kernels of different sizes demonstrate the efficiency of the proposed approach especially in small blur lengths compared to other algorithms.

1.3 Thesis Organization

The thesis is organized as follows:

Chapter 2 explains the meaning of motion blur, how it happens and how to model it in image processing. It introduces brief description of point spread functions (PSFs) and the main types of motion blur, the linear motion blur, and the non-linear motion blur with a survey of the most important algorithms.

Chapter 3 presents image deconvolution, with a survey of the most common techniques used, focusing on the lucy-richardson algorithm used in the proposed approach.

Chapter 4 introduces GA, where a detailed explanation for the different stages of the algorithm as the reproduction, crossover, and mutation is given. This is followed by a demonstration for the algorithm that is used in our study. Effects of the different parameters affecting the operation of the algorithm as the probability of mutation and the size of population are all investigated.

Chapter 5 presents how GA is used for linearly blurred images. The chapter includes the different trials of the goal function till the final attempt, and how the algorithm behaves in small and large blur lengths. Then the problem of ringing artifacts is discussed. Finally, experimental results of the GA are compared to some selected algorithms.

Chapter 6 introduces how GA is used to remove non-linear motion blur. This chapter also includes the different trials of the goal function, and how the image gradients histogram is used in the final goal function. Then it introduces experimental results and comparisons with the other algorithms.

Chapter 7 presents the accelerated version of the GA using Graphics Processing Unit (GPU) and includes the results that show the great speed-up achieved.

Chapter 8 contains the final conclusions of this work together with any possible improvements and further investigation for unsolved problems.