

### Wireless Sensor Network for Smart Border

#### A Thesis

Submitted in partial fulfillment for the requirements Of the degree of Master of Science in Electrical Engineering (Electronics and Communications Engineering)

### Submitted by

#### Hossam Omar Ahmed Omar

B.Sc. in Electrical Engineering Electronics and Communications Engineering Department El-Shorouk Academy, 2007

Supervised by

#### Prof. Hani Fikry

Electronics and Communications Engineering Department
Ain Shams University
Faculty of Engineering

### Dr. Ihab Adly

Electronics and Communications Engineering Department Faculty of Engineering, British university In Egypt Cairo 2014



## **Examination Committee**

Name	: Hossam Omar Ahmed Omar			
Thesis	: Wireless Sensor Network for Smart Bo	: Wireless Sensor Network for Smart Border		
Degree	: Master of Science in Electrical Engine	ering		
Name, Ti	itle and Affiliation	Signature		
<b>Prof. Salah Ibrahim Al Agouz</b> Electronics and Communications Engineering Department Institute of Engineering, El-Shorouk Academy				
Electronics	amed Amen Dessouky and Communications Engineering Department Engineering, Ain Shams University			
Electronics	Fikry Ragai and Communications Engineering Department Engineering, Ain Shams University			

Date: 16/12/2014



## **Approval Sheet**

: Wireless Sensor Network for Smart Border

: Master of Science in Electrical Engineering

: Hossam Omar Ahmed Omar

Name Thesis

Degree

Name, Title and Affiliation	Signature
<b>Prof. Hani Fikry</b> Electronics and Communications Engineering Department Faculty of Engineering, Ain Shams University	
<b>Dr. Ihab Adly</b> Electronics and Communications Engineering Department Faculty of Engineering, BUE	



#### **Statement**

This dissertation is submitted to Ain Shams University in partial fulfillment of the degree of Master of Science in Electrical Engineering (Electronics and Communications Engineering).

The work included in this thesis was carried out by the author at the department of Electronics and Communications Engineering, Faculty of Engineering, Ain Shams University, Cairo, Egypt.

No part of this thesis was submitted for a degree or qualifications at any other university or institution.

Name : Hossam Omar Ahmed Omar

Signature :

Date :



### **Curriculum Vitae**

Name of the researcher : Hossam Omar Ahmed

Date of Birth : 1 - 9 - 1985

Place of Birth : North Sinai

Nationality : Egyptian

First University Degree : B.Sc. in Electrical

Engineering
Electronics and
Communications

Faculty of Engineering, El-Shorouk Academy.

Date of Degree : July 2007

Current Job : Instructor in El-Shorouk

Academy

Name : Hossam Omar Ahmed

Signature :

Date :

### **Abstract**

The use of wireless sensor networks to protect sensitive facilities or international borders has recently attracted more and more attention. It has become a high-priority issue in many countries. In addition to the physical fences built for stopping illegal intruders from crossing the border, smart fencing has been proposed to extend intrusion detection capabilities. Event detection is a central component in numerous wireless sensor network (WSN) applications. In spite of this, the area of event description has not received enough attention. The majority of current event description approaches rely on using precise values to specify event thresholds. However this crisp values cannot adequately handle the imprecise sensor readings.

The Fuzzy Logic System (FLS), is known to be robust and has excellent immunity to external disturbances, can tolerate the unreliable and imprecise sensor readings, and much more intuitive and easier to use. In addition to Fuzzy Logic System, a hybrid event detection algorithm is also introduced and added to the proposed system to enhance the capability of noise reduction in the sensor output signals. Therefore, in this Thesis, Event-detection algorithm based on two layers, 12 bits resolution, fuzzy Logic system (FLS) is modeled using Matlab Simulink, and then designed with the same aspects using VHDL as a proposed design for each node in the wireless sensor Network, which significantly improves the accuracy of the event detection. Each sensor node has an acoustic signal sensor and 3-axis acceleration sensor to improve the precision of the detection system, as well as reducing false alarm rate specially in a noisy environment. Then, the simulation results from both models using Matlab and the VHDL design, have been compared and provided that the FPGA-based fuzzy controller is very close to the software-based controller using MATLAB. Finally, the proposed system has been tested and verified to show the detection ratio of the entire system, which is about 81.2%, the suggestions of improving this testing result is also illustrated in this thesis.

## Acknowledgement

All praise and glory go to Almighty Allah who gave me the strength and patience to carry out this work.

First and foremost gratitude is to the esteemed university, Ain Shams University, and its faculty of engineering members for their high quality education they supplied me with through my postgraduate studies.

My deep appreciation and gratitude go to my thesis advisors Prof. **Hani Fikry**, and Dr. **Ihab Adly**, for their constant guidance, support and valuable time they supplied me with through my work in this thesis.

I would like to express my sincere thanks to Dr. **Mohamed Elkhatib** for his outstanding suggestions and cooperation received during the study period.

Many thanks and appreciations go to my dear parents, my uncle Sheikh Saleh Abo Khalil and all his family members, my brother and my two sisters for their continuously encouragement and support, and my friends, especially, Mr. Ahmed Hesham, Mr. Ahmed Ashraf, and Mr. Shady Ahmed, for their prayers and Support, they really supplied me with through my postgraduate studies.

## **Table of Contents**

Abstract	vi
Acknowledgement	vii
List of Figures	X
List of Tables	xiii
List of Abbreviations	xiv
Chapter One Introduction	1
1.1 Thesis Motivation	1
1.2 Thesis Objectives	3
1.3 Thesis organization	
Chapter Two Survey of the WSN and Fuzzy Lo	ogic
Theory	5
2.1 Introduction	5
2.2 Survey of Wireless Sensor Network	
2.1.1 Challenges and Hurdles	
2.1.2 Sensor Networks Architecture	
2.1.3 Applications of Sensor Networks	11
2.3 Review of Fuzzy Logic Theory	15
2.3.1 Fuzzy Systems: Mamdani versus Sugeno .	17
2.3.2 Fuzzy Control	20
2.3.3 Fuzzy Logic Hardware Overview	23
2.3.4 Fuzzy VS Conventional Control	24
2.3.5 Hardware Implementation Techniques	26
2.3.6 Fuzzy Logic Hardware Implementation Co	_
2.4 Related Work on border surveillance	30
2.4.1 Stealth Detection of Mobile Targets	30
2.4.2 Evaders Detection with the Help of WSN.	32
2.4.3 Line in the Sand	33
2.4.4 Border Sense	34
2.4.5 Marine Surveillance Using Underwater/ V	Vireless
Sensor Networks	34

2.4.6 WSN and Neural Networks for Border Protect	
2.4.7 FleGSens: A Wireless Sensor Network for Border Surveillance	
Chapter Three Smart Border Surveillance	38
<ul><li>3.1 Introduction</li><li>3.2 Smart Border Surveillance</li><li>3.3 Event Detection Algorithm</li><li>3.4 Proposed FUZZY System for Border Monitoring</li></ul>	38 40
Chapter Four System Model Simulation and VHDI Hardware Implementation	
<ul> <li>4.1 Introduction</li> <li>4.2 MATLAB Simulation Results</li> <li>4.3 VHDL Simulation Results</li> <li>4.4 VHDL Hardware Implementation</li> <li>4.5 System Testing and Verification</li> </ul>	50 54 56
Chapter Five Conclusions and suggestions for Future Work	62
5.1 Conclusion	
Publication List	63
References	64
APPENDICES	69

## **List of Figures**

Figure 1.1 Egypt- Libya border crossing point example .1
Figure 1.2 SPWSS node2
Figure 2.1 Generic protocol stack for sensor networks9
Figure 2.2 Sensor nodes scattered in a sensor field11
Figure 2.3 Category 2 WSNs: point-to-point, generally-
single hop systems utilizing static12
Figure 2.4 Category 1 WSNs: multipoint-to-point,
multihop systems utilizing dynamic routing 13
Figure 2.5 Cooperative and non-cooperative nodes14
Figure 2.6 Fuzzy Membership function17
Figure 2.7 The basic configuration of a Fuzzy Logic
Controller21
Figure 2.8 Actual deployment in the test field and a high
level diagram of the topology31
Figure 2.9 (a) What pursuers really see a PEG; (b) WSN
increase visibility to pursuers32
Figure 2.10 An enclosed mote used in Line in the Sand
Project33
Figure 2.11 Hybrid combination of multimedia, ground,
mobile, and underground sensors for border
patrol32
Figure 2.12 (a) A simplified diagram of the underwater
sensor network to detect enemy water craft;
(b) A detailed diagram of an underwater
acoustic sensor node; (c) An overview of the
whole underwater acoustic sensor network 35
Figure 2.13 Experimental Sensor network deployment
for detecting ship movements36
Figure 3.1 Border Monitoring using WSN39
Figure 3.2 Deployed Fuzzy Logic System in each WSN
node along the wayside40
Figure 3.3 The response of the double sliding window
event-detection algorithm42
Figure 3.4 Proposed system Block diagram43

Figure 3.5 Proposed System First Layer System Model
Figure 3.6 Proposed System Second Layer System  Model
Figure 3.7 MFs for acoustic value in the first FLS layer
Figure 3.8 MFs for acoustic rate in the first FLS layer45 Figure 3.9 MFs for acceleration value in the first FLS layer
Figure 3.10 MFs for acceleration rate in the first FLS layer
Figure 3.11 MFs for Acoustic output decision in the first FLS layer46
Figure 3.12 MFs for Acceleration output decision in the first FLS layer46
Figure 3.13 MFs for the first FLS in the second FLS layer
Figure 3.14 MFs for the Modified alarm check signal rate of the first FLS in the second layer47
Figure 3.15 MFs for the second FLS in the second layer
Figure 3.16 MFs for the Modified alarm check signal rate of the second FLS in the second layer .47
Figure 3.17 MFs for output decision in the second FLS layer
Figure 3.18 Surface view of acoustic sensor probability with respect to Signal value and rate of change
Figure 3.19 Surface view of 1-axis acceleration sensor probability with respect to Signal value and rate of change
Figure 3.20 Surface view of second layer FLS probability with respect to outputs from the Acoustic FLS and 1-axis acceleration FLS.48

Figure 4.1 Sensor input signal value for both the two
sensors in the first case with the presence of
Gaussian Distributed Noise51
Figure 4.2 The corresponding sensors signal rate of
change in the first case51
Figure 4.3 The simulation result of output response of
the first layer FLC for Acoustic Sensor in the
first case51
Figure 4.4 The simulation result of output response of
the first layer FLS for 1-axis acceleration
Sensor in the first case51
Figure 4.5 The simulation result of output response of
the second layer FLS in the first case52
Figure 4.6 Sensor input signal value for both the two
sensors in the second case with the presence
of Gaussian Distributed Noise52
Figure 4.7 The corresponding sensors signal rate of
change in the second case
Figure 4.8 The simulation result of output response of
the first layer FLC for Acoustic Sensor
change in the second case53
Figure 4.9 The simulation result of output response of
the first layer FLS for 1-axis acceleration
Sensor change in the second case53
Figure 4.10 The simulation result of output response of
the second layer FLS change in the second
case53
Figure 4.11 fuzzy logic VHDL block diagram54
Figure 4.12 entire VHDL section design of the proposed
system55
Figure 4.13 Sensor input signal value for both the two
sensors in the first case with the presence of
Gaussian Distributed Noise using ModelSIM
55

Figure 4.14 Sensor input signal value for both the two	
sensors in the second case with the presence	
of Gaussian Distributed Noise using	
ModelSIM5	6
Figure 4.15 Typical FPGA design flow using simulation	
and RTL level synthesis5	
Figure 4.16 The proposed system implementation block	
diagram; (a) single node side; (b) sink side	
5	ð
Figure 4.17 The practical system prototype of a single	_
node (inside a case)5	9
Figure 4.18 The practical system prototype of a single	
node (unboxing)5	9
Figure 4.19 Proposed System GUI6	0
Figure 4.20 Runs experiment results6	0
List of Tables	
Table 2-1 Mamdani verses Sugeno[11, 12]2	0
Table 4-1 the compilation report summary of the total	_
system5	8
5,500111	J

## **List of Abbreviations**

ANN Artificial Neural Network

ASIC Application Specific Integrated Circuits

C1WSN Category 1 WSN

C2WSN Category 2 WSN

COG Center of Gravity

DOA Degree Of Aggregation

DSP Digital Signal Processing

FLC Fuzzy Logic Controller

FLC Fuzzy Logic Controller

FLIPS Fuzzy Logic Inference Per Second

FLS Fuzzy Logic System

FPGA Field Programmable Gate Array

GUI Graphical User Interface

IC Integrated Circuit

LAN Local Area Network

MEMS Micro Electro Mechanical Systems

MF Membership Function

NRE Non-Recurring Engineering

OS Operating System

PEG Pursuer Evaders Game

PID Proportional Integral Derivative

PIR Passive Infrared

PLD Programmable logic devices

R & D Research and development

RF Radio Frequency

RTL Register Transfer logic

SOC System on Chip

SPWSS Self-Powered Wireless Sensor System

T-S type Takagi-Sugeno type

VHDL VHSIC Hardware Description Language