



شبكة المعلومات الجامعية

بِسْمِ اللَّهِ الرَّحْمَنِ الرَّحِيمِ





شبكة المعلومات الجامعية



شبكة المعلومات الجامعية

التوثيق الالكتروني والميكرو فيلم

جامعة عين شمس

التوثيق الالكتروني والميكرو فيلم

قسم

نقسم بالله العظيم أن المادة التي تم توثيقها وتسجيلها
على هذه الأفلام قد اعدت دون أية تغيرات



يجب أن

تحفظ هذه الأفلام بعيداً عن الغبار

في درجة حرارة من 15 – 20 مئوية ورطوبة نسبية من 20-40 %

To be kept away from dust in dry cool place of
15 – 25c and relative humidity 20-40 %



شبكة المعلومات الجامعية



بعض الوثائق الأصلية تالفة



شبكة المعلومات الجامعية



بالرسالة صفحات
لم ترد بالأصل

**Accuracy Assessment for hand held GPS receivers
Supported with WASS/EGNOS Corrections and its
implication in Hydrographic survey**

BY

Eng. Alaa Al- din Hamdy Wahba Sharawi

**A Thesis submitted to
Faculty of Engineering - Cairo University
In Partial Fulfillment of the Requirements
For the Degree of MASTER OF SCIENCE**

In

CIVIL ENGINEERING

Under the supervision of

**Dr. Mohamed Shawki EL-Ghazali
Prof. of Surveying and Potogrammetry
Faculty of Engineering
Cairo University**

**Dr. Adel Hassan EL-Shazly
Assistant Prof. of Surveying Geodesy
Faculty of Engineering
Cairo University**

**Dr. Yasser Sherif al-Manadily
Assistant Prof. of Surveying Geodesy
Faculty of Engineering
Cairo University**

**FACULTY OF ENGINEERING, CAIRO UNIVERSITY,
GIZA, EGYPT**

2006

B

١١٤٧

Accuracy Assessment for Handheld GPS Receivers Supported with WASS/EGNOS Corrections and its Implication in Hydrographic Survey

By

Eng. Alaa Al-din Hamdy Wahba Sharawi
Military Technical college - 1990

A Thesis submitted to
Faculty of Engineering at Cairo University
In Partial Fulfillment of the Requirements
For the Degree of MASTER OF SCIENCE

In

CIVIL ENGINEERING

Approved by the
Examining Committee:

.....
.....

Prof. Dr. Mohamed Shawki Ahmad EL-Ghazali
Professor of Surveying and photogrametry
Faculty of Engineering, Cairo University

**Thesis Main
Advisor**

.....
.....

Prof. Dr. Ahmed Abed AL-Satar
Professor of Surveying and Geodesy
Faculty of Engineering, Shoubra, Zagazig University (Banha
Branch)

(Member)

.....
.....

Prof. Dr. Mohamed Safwat AL-Hoseny
Professor of Surveying and Geodesy
Faculty of Engineering, Cairo University

(Member)

.....
.....

Assistant Prof. Dr. Yasser Sherif al-Manadily
Assistant Professor of Surveying and Geodesy
Faculty of Engineering, Cairo University

Thesis Advisor

.....
.....

Assistant Prof. Dr. Adel Hassan EL-Shazly
Assistant Professor of Surveying and Geodesy
Faculty of Engineering, Cairo University

Thesis Advisor

FACULTY OF ENGINEERING, CAIRO UNIVERSITY
GIZA, EGYPT
2006

د. / مجدى صلاح نور الدين
رئيس مجلس القسم
٢٠٠٦ / ٤ / ٢

ACKNOLEGEEMENT

There are many people who, directly or indirectly, contributed to this endeavor, and to each the writer extends deep appreciation. How-ever some deserve special recognition.

It is my pleasure to gratefully acknowledge the assistance and express sincere gratitude to my major advisor, Dr. Mohammed shawki El-Ghazali for his continuous guidance, encouragement, and professional support during the course of this study. A very special thanks is also due to Dr. Yasser Sheif Al-Manadily professor, for his support and encouragement throughout my entire master program. Special recognition and appreciation is likewise extended to Dr. Adel Hassan El-Shazly. All of whom have contributed immensely toward my academic goals.

Appreciation is also expressed to general of military survey department who have contributed toward my degree. Without his assistance this endeavor would not have been possible.

ABSTRACT

The Global Positioning System (GPS) has changed the concept of surveying operations from on ground to sky measurements. GPS is designed primarily as a navigation system to satisfy both military and civilian needs for real - time positioning. The differential GPS (DGPS) technique has improved the positioning accuracy. It enables the using of GPS in various applications replacing the time consuming and costly traditional surveying techniques. The differential concept of GPS has been used with at least two receivers to satisfy the required accuracy and to overcome the selective availability (S.A.). After (S.A.) had been turned off, the differential GPS techniques have been improved and became available for the users through Omnistar Network Control Centers (NCC) and Beacons differential corrections. With the implementation of the Wide Area Augmentation System WAAS and the European Geostationary Navigation Overlay Service EGNOS corrections in the recent GPS receivers, it could be used in different engineering applications with no fees and based on the accuracy claimed by the manufactures.

In Egypt, the European Geostationary Navigation Overlay Service EGNOS corrections have covered most of the country. The Differential GPS (DGPS) accuracy based on these corrections may reach less than 3m as claimed by manufactures. Such accuracy may be satisfied by using even handheld GPS receivers. In this research, an overview for GPS system is introduced with emphasis on DGPS systems. Handheld GPS receivers supported with EGNOS corrections are presented and used in the experimental work. The coverage of EGNOS correction is presented. The claim of the manufacturers of the recent receivers supported with EGNOS of satisfying the accuracy of better than 3m was tested using the handheld GPS receivers. The accuracy was checked with respect to fixed control points and during kinematic process. Also, the way of obtaining and recording the data from handheld GPS (Magellan map330) is discussed and the National Marine Electronics Association NMEA format is presented and how it can be handled from receivers.

The interface of handheld GPS receivers with computer and download of data during and after survey, i.e. download of tracks and waypoints are covered. The use of handheld GPS receivers in navigation along predefined tracks is illustrated. The optimum use of handheld GPS receivers in positioning is studied compared to the points done with total stations. The capability of handheld GPS receivers in performing bathymetric survey during navigations along perspective tracks and during the survey of bed points is studied. The accuracy is given compared with the survey with total station.

The results of testing handheld GPS receivers supported with EGNOS corrections, prove that the accuracy of such equipment is 3m. It is recommend for using Handheld GPS with EGNOS correction in static positioning by turning on the receiver from the start of survey up to end (avoid to switch on and off GPS during static and kinematics). The accuracy of static positioning by GPS with EGNOS correction is less than 2m at night and less than 4m in the morning time. The recommend sample rate is 60 sec during the kinematics position when using Handheld GPS with EGNOS correction with speed 10 ~15km. The Handheld GPS with EGNOS correction can be used to support the navigation process during the Hydrographic survey with accuracy less than 2m and positioning of sounding during the Hydrographic survey with accuracy less than 4m.

Finally, The Handheld GPS receivers, supported with EGNOS corrections, based on the tested accuracy is recommend in some applications, like route survey, and hydrographic survey, for mapping with scale 1: 10.000 or smaller.

CONTENTS

	Page
ACKNOWLEDGMENTS	i
ABSTRACT	ii
CONTENTS	iv
LIST OF TABLES	vii
LIST OF FIGURES	viii
CHAPTER (1) Introduction	1-5
1.1 Introduction	1
1.2 Problem statement	3
1.3 Goals and Objectives	4
1.4 Thesis out line	4
CHAPTER (2) GPS/DGPS Technology	6-40
2.1 Introduction	6
2.2 Global Positioning System (GPS)	7-15
2.2.1 Introduction	7
2.2.2 GPS Error Sources	10
2.2.3 Geometric Dilution of Precision (GDOP) and Visibility	12
2.3 Differential GPS (DGPS)	15-34
2.3.1 Definition	15

2.3.2 Worldwide Beacon DGPS	17
2.3.3 OMNI STAR satellites	20
2.3.4 Satellite based augmentation systems	21
2.4 The Data of Handheld GPS Receivers supporting EGNOS Correction (NMEA) data	38
2.5 Summary	39
CHAPTER (3) Overview for Hydrographic Survey	41-48
3.1 Introduction	41
3.2 Underwater Depths Measurements during Hydrographic Survey	42
3.3 Positioning Techniques for Offshore Engineering Surveys	45
3.3.1 Sextant Resection Positioning	46
3.3.2 Triangulation/Intersection Positioning	49
3.3.3 Visual Positioning Methods	52
3.3.4 Tag Line Positioning Methods	54
3.3.5 Range-Azimuth Positioning Methods	57
3.3.6 Land-Based Electronic Positioning Systems	61
3.3.7 Global Positioning System Techniques	65
3.4 Summary	68
Chapter (4) Accuracy Evaluation of Handheld GPS Receivers supporting EGNOS Correction	69-94
4.1 Introduction	69
4.2 Equipments used	69
4.3 Testing of handheld GPS during Static positioning	70