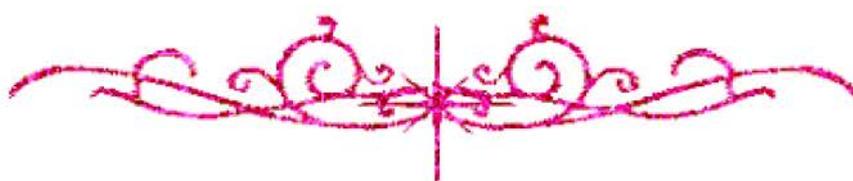


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لم ترد بالأصل



SUEZ CANAL UNIVERSITY
FACULTY OF ENGINEERING AND TECHNOLOGY
PORT-SAID
ELECTRICAL ENGINEERING DEPARTMENT

**PERFORMANCE ANALYSIS OF INVERTER-FED
PERMANENT MAGNET SYNCHRONOUS MOTOR**

A Thesis Submitted in Partial Fulfilment for the
Degree of Master of Science

BY

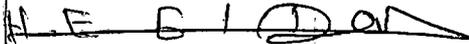
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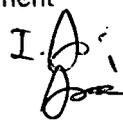
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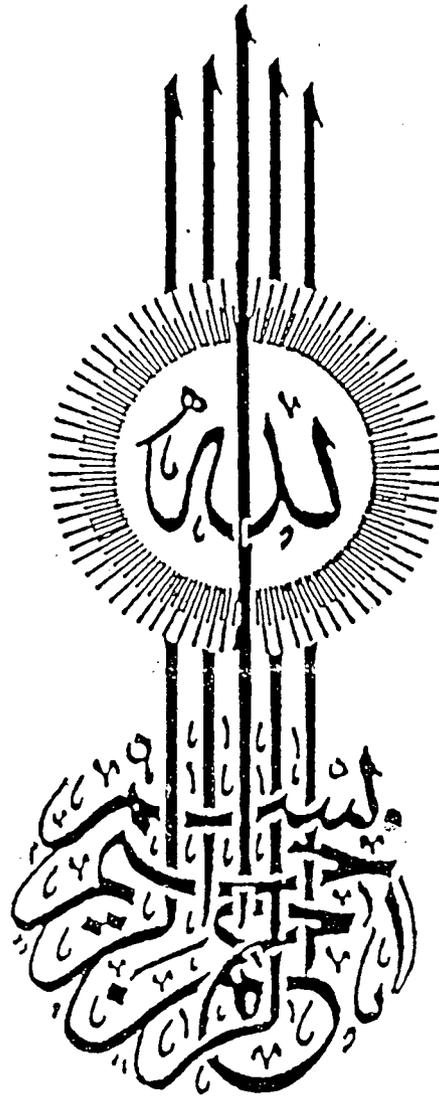


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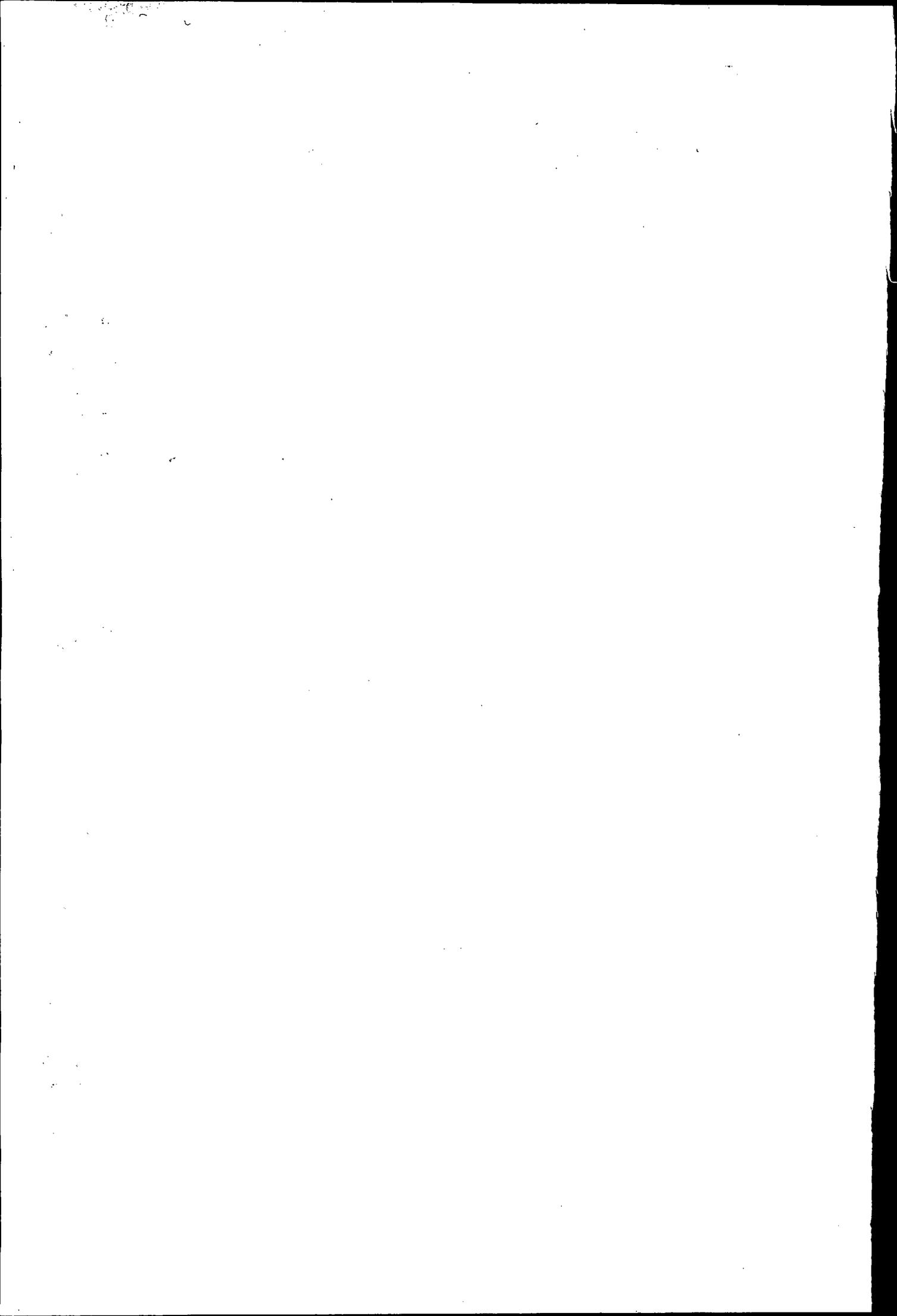






سبحانك

لأعلم لنا إلا ما علمتنا إنك أنت العليم الحكيم
صدق الله العظيم



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NOMENCLATURE

a , b	Fourier coefficients.
DF	Distortion factor.
F	Supply frequency, hz.
FR	Frequency ratio.
HF	Harmonic factor.
H	Inertia constant, sec.
I	Current, p.u.
L	Inductance, henery.
P	Power, p.u.
R	Resistance, p.u.
rpw	relative pulse - width.
S	Slip.
T	Torque, p.u.
t	Time, sec.
V,E	Voltage, p.u.
X	Reactance, p.u.
2p	Number of poles.
2m	Number of pulses per half - cycle.
K_D	Damping torque coefficient, p.u./rad/sec.
K_S	Synchronizing torque coefficient, p.u./rad.
δ	Load angle degree.
ω	Angular velocity, rad/sec.
ρ	Differential operator.
λ, ψ	Flux linkage ($\psi = \omega\lambda$).

θ	Rotor displacement, degree.
α	Triggering angle, degree.
τ	Theoretical maximum pulse - width.
β	Variable pulse - width.
ϕ	Flux wb.
φ	Power factor.

SUB AND SUPERSCRIPTS

d	Direct axis.
q	Quadrature axis.
d.c.	Direct current.
n	Harmonic order.
f	Field.
s	Stator.
r	Rotor.
m	Mutual.
l	Leakage.
pm	Permanent magnet.
e	Electrical.
0	Zero sequence.
a,b,c	Three phase set.
m	Motor.
L	Load.
rms	Root mean square.